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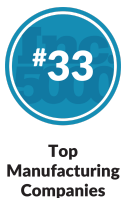
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MaxBotix Inc., Makes Inc. 5000 List For Second Time

Author: Kathy Kostal Date: 08-31-2016



Inc. Magazine Unveils 35th Annual List of America's Fastest Growing Private Companies—the Inc. 5000. MaxBotix Inc., Ranks No. 1752 on the 2016 Inc. 5000 with Three-Year Sales

Growth of 213%.
[Click here](#) for full article.

Raspberry Pi TTL Tutorial

Author: Cody Carlson Date: 08-02-2016



MaxSonar sensors offer a variety of outputs including TTL serial data. This tutorial guides you through the process of setting up your Raspberry Pi 3 with a MaxBotix sensor. [Click here](#) for full article.

Packaging Options for the MaxSonar Sensors

Author: Scott Wielenberg Date: 07-26-2016

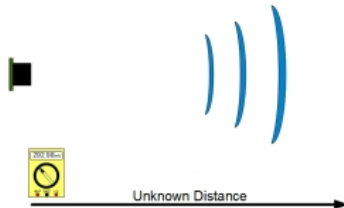


MaxBotix offers an expanded range of packaging options for many of our sensors. Each option provides unique benefits to certain mounting integrations. This article provides a brief overview of each option. [Click here](#) for full article.

Finding Distance Using Analog Voltage

| Written By: Tom Bonar | DatePosted: 07-10-2012 |

How to Calculate Distance from the Pin 3



The Analog Voltage pin on the MaxSonar family of sensors has been the most popular output for our users. All of the MaxSonar sensors have this output included. This guide will give a look into how to use it for obtaining the distance to the target being detected. The Analog Voltage output is scaled on all sensors to the power input of the sensor. The Analog Voltage output will output a linear voltage that gets larger as a target increases in distance from the sensor. This scaling will be outlined with each sensor family. For all examples the power input is +5VDC.

Our standard LV-MaxSonar and XL-MaxSonar sensors assume the temperature is 22.5 degrees celsius. These sensors do not apply temperature compensation as the air temperature changes. Our HR-MaxSonar sensors do apply automatic temperature compensation as the air temperature changes. To apply temperature compensation to your part please see the Temperature Compensation PDF [here](#)

LV-MaxSonar Sensors

This is for the LV-MaxSonar-EZ, LV-MaxSonar-WR, and LV-MaxSonar-WRC. All of our LV-MaxSonar sensors range to targets in inches. The formula for the voltage scaling on an LV-MaxSonar sensor family is:

$$[(V_{cc}/512) = V_i]$$

V_{cc} = Supplied Voltage

V_i = Volts per inch (Scaling)

Example 1

$$[(5.0V/512) = 0.009766V \text{ per inch} = 9.766mV \text{ per inch}]$$

Calculating the Range

Once you know the voltage scaling it is easy to properly calculate the range. The range formula is:

$$[(V_m/V_i) = R_i]$$

V_m = Measured Voltage

V_i = Volts per Inch (Scaling)

R_i = Range in inches

Example 2:

If your multimeter shows a measurement 292.98mV then you use the calculations as follows:

$$[(292.98mV/9.766mV) = 30 \text{ inches}]$$

Example 3:

To work backward and verify your calculation is correct use the inverse formula:

$$[(R_i \times V_i) = V_m]$$

$$[(30 \times 9.766) = 292.98]$$

Using an LV-MaxSonar with an ADC (Analog Digital Converter)

When using an LV-MaxSonar with an ADC, verify that the sensor and micro-controller are referencing the same power supply and ground. This also assumes that the ADC being used is perfectly accurate.

When reading the sensor's output with the scaling in inches with a 10-bit ADC, divide the ADC output by 2 for the range in inches.

If the ADC output reads 508 (maximum output) the range in inches is 254 inches. If the ADC output reads 250 the range in inches is 125 inches.

Standard XL-MaxSonar Sensors

This is for the XL MaxSonar EZ, XL-MaxSonar-AE, XL MaxSonar WR, and XL MaxSonar WRC. This formula does not include scaling for our 10 meter sensors: XL-MaxSonar-WRL1/WRLA1, XL-MaxSonar-EZL0/AEL0, and XL-MaxSonar-EZL1/AEL1.

The voltage scaling formula for the standard XL MaxSonar sensor family is:

$$[(V_{cc}/1024) = V_{cm}]$$

V_{cc} = Supplied Voltage

V_{cm} = Volts per cm (Scaling)

Example 1:

The formula should read:

$$[(5.0V/1024) = 0.004883V \text{ per cm} = 4.883mV \text{ per cm}]$$

The MaxBotix RMA Process Guide

Author: Scott Wielenberg Date: 07-18-2016



When providing support, our technical support team may determine that further testing at our facility is the best way to help resolve the issue that you are facing. At this point, they will start the Return Merchandise Authorization (RMA) process. This article will explain what you can expect as your ultrasonic sensor travels through our RMA process.
[Click here](#) for full article.

Important Considerations for Using an Ultrasonic Sensor Inside of a Pipe

Author: Scott Wielenberg Date: 07-11-2016



Many customers have requested the option to mount an ultrasonic sensor in a pipe. During the testing and development cycle, we discovered a number of considerations and requirements that must be met for the application to be successful. When all of these are met, a user may be able to achieve the desired level of success for measuring the liquid level inside of a pipe.
[Click here](#) for full article.

Grand Opening of Facility Expansion

Author: Jenney Grover Date: 06-28-2016



On April 19th, we welcomed our supporters to join us for the Grand Opening of the Build Out. Bob and Nita Gross gave a tour of the build out and their vision for the space. We continue to be in awe of the support from our community, our employees, our distributors, and our customers. Thank you for the many years of support, and we look forward to serving you in the years to come.
[Click here](#) for full article.

News Archive

New Product Signup

Signup for notification of our exciting new products and periodic new letters. We are excited to provide the latest information from MaxBotix Inc.

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Calculating the Range

Once you know the voltage scaling you can properly calculate the range.

The range formula is:

$$[(V_m/V_{cm}) = R_{cm}]$$

V_m = Measured Voltage

V_{cm} = Volts per cm (Scaling)

R_{cm} = Range in cm

Example 2:

If the multimeter shows a reading of 439.47mV, then you use the calculation as follows:
[(439.47mV/4.883mV) = cm] in this case the range is 90cm

Example 3:

To work backward and verify your calculation is correct use the inverse formula:

$$[(R_{cm} \times V_{cm}) = V_m]$$

$$[(90 \times 4.883mV) = 439.47mV]$$

Using a Standard Range XL-MaxSonar with an ADC (Analog Digital Converter)

When using a standard XL-MaxSonar with an ADC, verify that the sensor and micro-controller are referencing the same power supply and ground. This also assumes that the ADC being used is perfectly accurate.

When reading the sensor's output with the scaling in centimeters with a 10-bit ADC, the range can be read directly off the ADC.

If the ADC output reads 700 the range in centimeters is 700 centimeters. If the ADC output reads 200 the range in centimeters is 200 centimeters.

XL-MaxSonar Long Range Sensors

For the 10meter long range sensors the calculation formula is

$$[(V_{cc}/1024) = V_{2cm}]$$

V_{cc} = Supplied Voltage

V_{2cm} = V per every 2 cm

Due to a limitation of hardware the Analog Voltage output steps in 2cm increments.

The formula to find the final distance is

$$[(V_m/V_{2cm})=U] \times 2 = cm$$

V_m = Volts measured

V_{2cm} = V per every 2 cm

U = half measurement

Example 1:

Your multimeter has a reading of 439.47mV.

$$[(439.47/4.883)=90] \times 2 = 180cm$$

Example 2:

To work backwards and verify correct calculation us the following formula

$$[(cm/2) \times V_{2cm}]=V_m$$

If you input the calculated range from Example 1 of 180cm into the formula, your reverse formula should read

$$[(180/2) \times 4.883]=439.47mv$$

Using a Long Range XL-MaxSonar with an ADC (Analog Digital Converter)

When using a standard XL-MaxSonar with an ADC, verify that the sensor and micro-controller are referencing the same power supply and ground. This also assumes that the ADC being used is perfectly accurate.

When reading the sensor's output with the scaling in centimeters with a 10-bit ADC, the range output has a 2cm resolution.

If the ADC output reads 500 the range in centimeters is 1000 centimeters. If the ADC output reads 200 the range in centimeters is 400 centimeters.

5-Meter HR-MaxSonar sensors

This is our newest line of sensors. To calculate the distance using voltage please use the following formula

$$(V_{cc}/1024)=V_{5mm}$$

V_{cc} = supplied voltage

V_{5mm} = Volts per 5mm

Due to a limitation within the hardware of the sensor the Analog Voltage steps in 5-mm increments.

Example 1

$$(5/1024)=V_{5mm} \text{ or } 0.004885V (4.883mV) \text{ per } 5 \text{ mm}$$

After the voltage scaling has been found, range calculation is now able to be done.

To calculate range use the formula:

$$(V_m/V_{5mm}) \times 5 = R_{mm}$$

Vm = Volts Measured
V5mm = Volts per 5 mm
Rmm = Range in mm

Example 2

The multimeter being used shows a voltage of 2.441V (2441.4mV). To find the distance the formula would look like
 $(2441.4/4.883) \times 5 = R_{mm}$
For this example the Range in millimeters is 2500 millimeters

Example 3

To verify this is correct use the following formula:
 $(R_{mm}/5) \times V_{5mm} = V_m$

So the reverse calculation would look like:
 $(2500/5) \times 0.004883 = V_m$
After calculation the Vm should read 2441.4mV or 2.441V

Using a 5-Meter HR-MaxSonar with an ADC (Analog Digital Converter)

When using a 5-meter HR-MaxSonar with an ADC, verify that the sensor and micro-controller are referencing the same power supply and ground. This also assumes that the ADC being used is perfectly accurate.

Using a 10bit analog to digital convertor, one can read the analog voltage bits (i.e. 0 to 1024) directly and just multiply the number of bits in the value by 5 to yield the range in mm. For example, 60 bits corresponds to 300-mm (where $60 \times 5 = 300$), and 1000 bits corresponds to 5000-mm (where $1000 \times 5 = 5000$ -mm).

10-Meter HR-MaxSonar sensors

This is our newest line of sensors. To calculate the distance using voltage please use the following formula

$(V_{cc}/1024) = V_{10mm}$
Vcc = supplied voltage
V10mm = Volts per 10mm

Example 1

$(5/1024) = V_{10mm} = 0.004883$ in this case V10mm will be 0.004883V or 4.883mV.

After the voltage scaling has been found, range calculation is now able to be done.

To calculate range use the formula:
 $(V_m/V_{10mm}) \times 10 = R_{mm}$

Vm = Volts Measured
V10mm = Volts per 10 mm
Rmm = Range in mm

Example 2

The multimeter being used shows a voltage of 1.2207V (1220.7mV). To find the distance the formula would look like
 $(1220.7/4.883) \times 10 = R_{mm}$
For this example the Range in millimeters is 2500 millimeters

Example 3

To verify this is correct use the following formula:
 $(R_{mm}/10) \times V_{10mm} = V_m$

So the reverse calculation would look like:
 $(2500/10) \times 0.004883 = V_m$
After calculation the Vm should read 1220.7mV or 1.2207V

Using a 10-Meter HR-MaxSonar with an ADC (Analog Digital Converter)

When using a 10-meter HR-MaxSonar with an ADC, verify that the sensor and micro-controller are referencing the same power supply and ground. This also assumes that the ADC being used is perfectly accurate.

Using a 10bit analog to digital convertor, one can read the analog voltage bits (i.e. 0 to 1024) directly and just multiply the number of bits in the value by 10 to yield the range in mm. For example, 30 bits corresponds to 300-mm (where $30 \times 10 = 300$), and 1000 bits corresponds to 10,000-mm (where $1000 \times 10 = 10,000$ -mm).

Products related to the Article Above

[HRLV-MaxSonar-EZ0](#)



[XL-MaxSonar-EZ4](#)



[HRXL-MaxSonar-WRC](#)



